

Orthogonal Similarity Reductions in Eigenvalue Algorithms

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THE
UNIVERSITY
OF RHODE ISLAND

Introduction

Definition: An *eigenpair* (λ, x) of an $n \times n$ matrix A is a scalar $\lambda \in \mathbb{R}$ (*eigenvalue*) and nonzero vector $x \in \mathbb{R}^n$ (*eigenvector*) such that

$$Ax = \lambda x.$$

Our focus is on the *symmetric* eigenvalue problem—where $A = A^T$.

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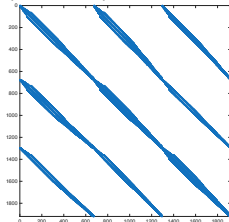
Small and Dense A

Iterative algorithms may be unnecessary

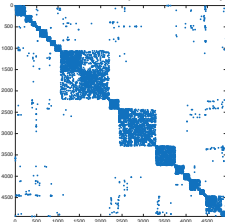
Large and Sparse A

Goal: Compute a few of the largest eigenpairs

Finite difference model
($n = 1919$)



Adjacency matrix
($n = 4941$)



Lanczos Factorization

Goal: Approximate largest eigenpairs $\{(\lambda_i, x_i)\}_{i=1}^k$ of large, symmetric A .

Key Idea: Project A onto a much smaller m -dimensional subspace.

The *Lanczos Algorithm* constructs this subspace so that the projection is **tridiagonal**.

$$AP_m = P_m T_m + f e_m^T \quad \Leftrightarrow \quad T_m = P_m^T A P_m.$$

$$\begin{bmatrix} A \end{bmatrix} \begin{bmatrix} P_m \end{bmatrix} = \begin{bmatrix} P_m \end{bmatrix} \begin{bmatrix} T_m \end{bmatrix} + \begin{bmatrix} \end{bmatrix} \begin{bmatrix} f \end{bmatrix}$$

** This is the cornerstone of MATLAB's 'eigs' command!

Eigenpairs of T_m

$$\begin{bmatrix} A \end{bmatrix} \begin{bmatrix} P_m \end{bmatrix} = \begin{bmatrix} P_m \end{bmatrix} \begin{bmatrix} \diagdown \\ T_m \end{bmatrix} + \begin{bmatrix} f \end{bmatrix}$$

Eigenpairs (θ, y) of T_m are used to approximate those of A :

$$T_m y = \theta y \quad \Rightarrow \quad A(P_m y) = \theta(P_m y) + f e_m^T y.$$

We call $(\theta, P_m y)$ a **Ritz pair** of A .

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Deflate out the $m - k$ “bad” eigenvalues of T_m via an orthogonal Q :

$$\begin{bmatrix} Q^T \end{bmatrix} \begin{bmatrix} \diagdown \\ T_m \end{bmatrix} \begin{bmatrix} Q \end{bmatrix} = \begin{bmatrix} \text{green square} \\ \diagdown \\ \tilde{T}_m \end{bmatrix}.$$

Creating the Arrowhead

How do we create Q so that $\begin{bmatrix} Q^T \\ \end{bmatrix} \begin{bmatrix} \diagdown \\ T_m \\ \diagup \end{bmatrix} \begin{bmatrix} Q \\ \end{bmatrix} = \begin{bmatrix} \text{green box} \\ \diagdown \\ \tilde{T}_m \\ \diagup \end{bmatrix} ?$

Let $\bar{P}_{k+1} = \underbrace{[P_m Y_k \quad f/\beta]}_{\text{Ritz vectors}}$ where $\beta = \|f\|$. One can show that

$$\bar{P}_{k+1}^T A \bar{P}_{k+1} = D_{k+1} = \begin{bmatrix} \theta_1 & & & & \beta y_{m,1} \\ & \theta_2 & & & \beta y_{m,2} \\ & & \ddots & & \vdots \\ & & & \theta_k & \beta y_{m,k} \\ \beta y_{m,1} & \beta y_{m,2} & \dots & \beta y_{m,k} & * \end{bmatrix}.$$

So the projection of A on \bar{P}_{k+1} basis is not tridiagonal ...

Arrowhead \rightarrow Tridiagonal

Remedy: "Tridiagonalize" the arrowhead D_{k+1} so that

$$\begin{bmatrix} \overline{Q}_k^T & & \\ & D_{k+1} & \\ & & \overline{Q}_k \end{bmatrix} = \begin{bmatrix} & & \\ & & \\ & & \overline{T}_{k+1} \end{bmatrix}.$$

Arrowhead \rightarrow Tridiagonal

Remedy: "Tridiagonalize" the arrowhead D_{k+1} so that

$$\begin{bmatrix} \overline{Q}_k^T \\ 1 \end{bmatrix} \begin{bmatrix} \diagdown \\ D_{k+1} \\ \diagup \end{bmatrix} \begin{bmatrix} \overline{Q}_k \\ 1 \end{bmatrix} = \begin{bmatrix} \diagdown \\ \overline{T}_{k+1} \\ \diagup \end{bmatrix}.$$

With the special 1 in \overline{Q}_k , we can truncate and obtain

$$\overline{Q}_k^T D_k \overline{Q}_k = \overline{T}_k \Rightarrow \begin{bmatrix} \overline{Q}_k^T \\ 1 \end{bmatrix} \begin{bmatrix} \diagdown \\ D_k \\ \diagup \end{bmatrix} \begin{bmatrix} \overline{Q}_k \\ 1 \end{bmatrix} = \begin{bmatrix} \diagdown \\ \overline{T}_k \\ \diagup \end{bmatrix}.$$

All Together ...

$$\begin{bmatrix} \bar{Q}_k^T \\ \phantom{\bar{Q}_k^T} \end{bmatrix} \begin{bmatrix} \diagdown \\ D_k \end{bmatrix} \begin{bmatrix} \bar{Q}_k \\ \phantom{\bar{Q}_k} \end{bmatrix} = \begin{bmatrix} \diagdown \\ \bar{T}_k \end{bmatrix}$$

From $T_m Y_m = Y_m \Theta_m$ we get

$$Y_m^T T_m Y_m = \begin{bmatrix} D_k = \Theta_k & \\ & \Theta_{m-k} \end{bmatrix} = \begin{bmatrix} \bar{Q}_k^T \bar{T}_k \bar{Q}_k^T & \\ & \Theta_{m-k} \end{bmatrix}.$$

After some rearranging:

$$\begin{bmatrix} Y_k \bar{Q}_k & \\ & Y_{m-k} \end{bmatrix}^T T_m \begin{bmatrix} Y_k \bar{Q}_k & \\ & Y_{m-k} \end{bmatrix} = \begin{bmatrix} \bar{T}_k & \\ & \Theta_{m-k} \end{bmatrix}$$

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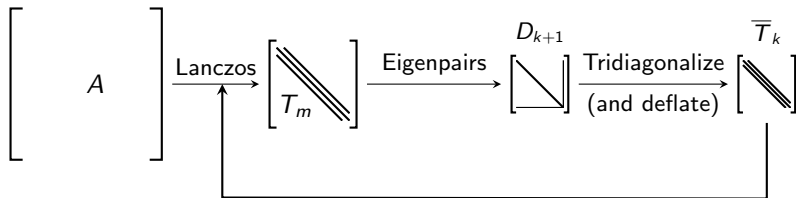
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This accomplishes our goal: find orthogonal $Q \in \mathbb{R}^{m \times m}$ so that

$$\begin{bmatrix} Q^T \\ \vdots \\ \vdots \end{bmatrix} \begin{bmatrix} \diagdown \\ T_m \\ \diagup \end{bmatrix} \begin{bmatrix} Q \\ \vdots \\ \vdots \end{bmatrix} = \begin{bmatrix} \diagdown \\ \tilde{T}_m \\ \diagup \end{bmatrix}.$$

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- The arrowhead \rightarrow tridiagonal conversion gives a new insight into the **mathematically equivalent** methods for restarting Lanczos:

$$\underbrace{\text{Keeping Ritz vectors } Y_k}_{\text{"Thick Restarts"}} = \underbrace{\text{Deflating } m - k \text{ "bad" Ritz values}}_{\text{"Implicit Restarts"}}$$

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- Moreover, numerical tests show greater accuracy at deflating multiple eigenvalues compared to, e.g., implicit QR algorithm.

$$\begin{bmatrix} Q^T \\ \diagdown \\ T_m \\ \diagup \end{bmatrix} \begin{bmatrix} Q \\ \diagup \\ \tilde{T}_m \\ \diagdown \end{bmatrix} = \begin{bmatrix} \diagdown \\ \tilde{T}_m \\ \diagup \end{bmatrix}$$

Example: Tridiagonal T_{31} with main diagonal $15, \dots, 1, 0, 1, \dots, 15$ and sub/super-diagonal 1's.

For $k = 15$: deflation using QR algorithm is 10^{-4}
deflation using arrowhead method is 10^{-14} !

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- We extended this to bidiagonalization and the SVD for restarting the GKL algorithm.

Thank you!